

Product data sheet

Specifications



Variable speed drive, Altivar Process ATV900, ATV930, 160 kW, 400/480 V, w/o braking unit, IP00

ATV930C16N4C

Product availability : Stock - Normally stocked in distribution facility

Price* : 20,961.60 USD

Main

Range of Product	Altivar Process ATV900	
Device Application	Industrial Application	
Product or Component Type	Variable speed drive	
Product destination	Synchronous motors Asynchronous motors	
Product Specific Application	Process for industrial	
Variant	Without braking chopper Standard version	
Phase	3 phase	
Mounting Mode	Wall mount	
Communication port protocol	Modbus serial Modbus TCP EtherNet/IP	
[Us] rated supply voltage	380...480 V -	
Motor power kW	160.0 kW normal duty 132.0 kW heavy duty	
Maximum Horse Power Rating	250.0 hp normal duty 200.0 hp heavy duty	نميadow
Continuous output current	302 A 2.5 kHz normal duty 250 A 2.5 kHz heavy duty	
EMC filter	Integrated With EMC plate option	
IP degree of protection	IP21	
Degree of protection	UL type 1	
Option module	Slot A communication module Profibus DP V1 Slot A communication module PROFINET Slot A communication module DeviceNet Slot A communication module EtherCAT Slot A communication module CANopen daisy chain RJ45 Slot A communication module CANopen SUB-D 9 Slot A communication module CANopen screw terminals Slot A/slot B/slot C digital and analog I/O extension module Slot A/slot B/slot C output relay extension module Slot B 5/12 V digital encoder interface module Slot B analog encoder interface module Slot B resolver encoder interface module communication module Ethernet Powerlink	
Discrete input logic	16 preset speeds	نميadow
Asynchronous motor control profile	Variable torque standard Constant torque standard	

* Price is "List Price" and may be subject to a trade discount – check with your local distributor or retailer for actual price.

	Optimized torque mode
Synchronous motor control profile	Permanent magnet motor Synchronous reluctance motor
Maximum output frequency	599 Hz
Switching frequency	1...8 kHz adjustable 2.5...8 kHz with derating factor
Nominal switching frequency	2.5 kHz
Line current	284.0 A 380 V normal duty) 237.0 A 380 V heavy duty) 262.0 A 480 V normal duty) 213.0 A 480 V heavy duty)
Apparent power	201.3 kVA 480 V normal duty) 161.4 kVA 480 V heavy duty)
Maximum transient current	362 A 60 s normal duty) 375 A 60 s heavy duty)
Network Frequency	50-60 Hz
Prospective line Isc	50 kA

Complementary

Discrete input number	10
Discrete input type	DI1...DI8 programmable, 24 V DC <= 30 V)3.5 kOhm DI7, DI8 programmable as pulse input 0...30 kHz, 24 V DC <= 30 V) STOA, STOB safe torque off, 24 V DC <= 30 V> 2.2 kOhm
Discrete output number	2
Discrete output type	Logic output DQ+ 0...1 kHz <= 30 V DC 100 mA Programmable as pulse output DQ+ 0...30 kHz <= 30 V DC 20 mA Logic output DQ- 0...1 kHz <= 30 V DC 100 mA
Analogue input number	3
Analogue input type	AI1, AI2, AI3 software-configurable voltage 0...10 V DC 30 kOhm 12 bits AI1, AI2, AI3 software-configurable current 0...20 mA/4...20 mA 250 Ohm 12 bits
Analogue output number	2
Analogue output type	Software-configurable voltage AQ1, AQ2 0...10 V DC 470 Ohm 10 bits Software-configurable current AQ1, AQ2 0...20 mA 500 Ohm 10 bits
Relay output number	3
Relay output type	Configurable relay logic R1 fault relay NO/NC 100000 cycles Configurable relay logic R2 sequence relay NO 1000000 cycles Configurable relay logic R3 sequence relay NO 1000000 cycles
Maximum switching current	Relay output R1 resistive, cos phi = 1 3 A 250 V AC Relay output R1 resistive, cos phi = 1 3 A 30 V DC Relay output R1 inductive, cos phi = 0.4 7 ms 2 A 250 V AC Relay output R1 inductive, cos phi = 0.4 7 ms 2 A 30 V DC Relay output R2, R3 resistive, cos phi = 1 5 A 250 V AC Relay output R2, R3 resistive, cos phi = 1 5 A 30 V DC Relay output R2, R3 inductive, cos phi = 0.4 7 ms 2 A 250 V AC Relay output R2, R3 inductive, cos phi = 0.4 7 ms 2 A 30 V DC
Minimum switching current	Relay output R1, R2, R3 5 mA 24 V DC
Physical interface	Ethernet 2-wire RS 485
Connector Type	2 RJ45 1 RJ45
Method of access	Slave Modbus TCP
Transmission Rate	10, 100 Mbits 4.8 kbps 9600 bit/s 19200 bit/s
Transmission frame	RTU
Number of addresses	1...247
Data format	8 bits, configurable odd, even or no parity

<u>Type of polarization</u>	No impedance
<u>4 quadrant operation possible</u>	False
<u>Acceleration and deceleration ramps</u>	Linear adjustable separately from 0.01...9999 s
<u>Motor slip compensation</u>	Automatic whatever the load Can be suppressed Adjustable Not available in permanent magnet motor law
<u>Braking to standstill</u>	By DC injection
<u>Brake chopper integrated</u>	False
<u>Maximum Input Current per Phase</u>	284.0 A
<u>Maximum output voltage</u>	480.0 V
<u>Relative symmetric network frequency tolerance</u>	5 %
<u>Base load current at high overload</u>	250.0 A
<u>Base load current at low overload</u>	302.0 A
<u>Power dissipation in W</u>	Forced convection 3507 W 380 V 2.5 kHz Natural convection 405 W 380 V 2.5 kHz
<u>With safety function Safely Limited Speed (SLS)</u>	True
<u>With safety function Safe brake management (SBC/SBT)</u>	True
<u>With safety function Safe Operating Stop (SOS)</u>	False
<u>With safety function Safe Position (SP)</u>	False
<u>With safety function Safe programmable logic</u>	False
<u>With safety function Safe Speed Monitor (SSM)</u>	False
<u>With safety function Safe Stop 1 (SS1)</u>	True
<u>With safety function Safe Stop 2 (SS2)</u>	False
<u>With safety function Safe torque off (STO)</u>	True
<u>With safety function Safely Limited Position (SLP)</u>	False
<u>With safety function Safe Direction (SDI)</u>	False
<u>Protection type</u>	Thermal protection motor Safe torque off motor Motor phase break motor Thermal protection drive Safe torque off drive Overheating drive Overcurrent between output phases and earth drive Overload of output voltage drive Short-circuit protection drive Motor phase break drive Overvoltages on the DC bus drive Line supply overvoltage drive Line supply undervoltage drive Line supply phase loss drive Overspeed drive Break on the control circuit drive
<u>Quantity per Set</u>	1
<u>Width</u>	12.60 in (320 mm)

Height	33.54 in (852 mm)
Depth	15.47 in (393 mm)
Net Weight	180.78 lb(US) (82 kg)
Electrical connection	<p>Control screw terminal 0.5...1.5 mm² AWG 20...AWG 16 Line side screw terminal 2 x 95...3 x 120 mm² AWG 3/0...300 kcmil Motor screw terminal 2 x 95...3 x 120 mm² AWG 3/0...300 kcmil DC bus screw terminal 2 x 95...3 x 120 mm² AWG 3/0...300 kcmil</p> <p>10/100 Mbit/s Ethernet IP/Modbus TCP 4.8, 9.6, 19.2, 38.4 kbit/s Modbus serial</p>
Exchange mode	<p>Half duplex, full duplex, autonegotiation Ethernet IP/Modbus TCP</p> <p>8 bits, configurable odd, even or no parity Modbus serial</p> <p>No impedance Modbus serial</p> <p>1...247 Modbus serial</p>
Supply	<p>External supply for digital inputs 24 V DC 19...30 V), <1.25 mA overload and short-circuit protection Internal supply for reference potentiometer (1 to 10 kOhm) 10.5 V DC +/- 5 %, <10 mA overload and short-circuit protection Internal supply for digital inputs and STO 24 V DC 21...27 V), <200 mA overload and short-circuit protection</p>
Local signalling	<p>Local diagnostic 3 LED mono/dual colour) Embedded communication status 5 LED dual colour) Communication module status 2 LED dual colour) Presence of voltage 1 LED red)</p>
Input compatibility	<p>DI1...DI8 discrete input level 1 PLC EN/IEC 61131-2 DI7, DI8 pulse input level 1 PLC IEC 65A-68 STOA, STOB discrete input level 1 PLC EN/IEC 61131-2</p> <p>Positive logic (source) DI1...DI8), < 5 V, > 11 V Negative logic (sink) DI1...DI8), > 16 V, < 10 V Positive logic (source) DI7, DI8), < 0.6 V, > 2.5 V Positive logic (source) STOA, STOB), < 5 V, > 11 V</p>
Sampling duration	<p>2 ms +/- 0.5 ms DI1...DI8) - discrete input 5 ms +/- 1 ms DI7, DI8) - pulse input 1 ms +/- 1 ms AI1, AI2, AI3) - analog input 5 ms +/- 1 ms AQ1, AQ2) - analog output</p>
Accuracy	<p>+/- 0.6 % AI1, AI2, AI3 for a temperature variation 60 °C analog input +/- 1 % AQ1, AQ2 for a temperature variation 60 °C analog output</p>
Linearity error	<p>AI1, AI2, AI3 +/- 0.15 % of maximum value analog input AQ1, AQ2 +/- 0.2 % analog output</p>
Refresh time	Relay output R1, R2, R3) 5 ms +/- 0.5 ms)
Isolation	Between power and control terminals
Environment	
Operating altitude	<= 3280.84 ft (1000 m) without derating 1000...4800 m with current derating 1 % per 100 m
Operating position	Vertical +/- 10 degree
Product Certifications	UL CSA TÜV
Marking	CE
Standards	UL 508C EN/IEC 61800-3 EN/IEC 61800-5-1 IEC 61000-3-12 IEC 60721-3 IEC 61508 IEC 13849-1
Maximum THDI	<48 % full load IEC 61000-3-12
Assembly style	Enclosed
Electromagnetic compatibility	<p>Electrostatic discharge immunity test level 3 IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 IEC 61000-4-5 Conducted radio-frequency immunity test level 3 IEC 61000-4-6</p>

<u>Environmental class (during operation)</u>	Class 3C3 according to IEC 60721-3-3 Class 3S3 according to IEC 60721-3-3
<u>Maximum acceleration under shock impact (during operation)</u>	150 m/s ² at 11 ms
<u>Maximum acceleration under vibrational stress (during operation)</u>	10 m/s ² at 13...200 Hz
<u>Maximum deflection under vibratory load (during operation)</u>	1.5 mm at 2...13 Hz
<u>Permitted relative humidity (during operation)</u>	Class 3K5 according to EN 60721-3
Volume of cooling air	158506.07 Gal/hr(US) (600 m ³ /h)
<u>Overvoltage category</u>	III
<u>Regulation loop</u>	Adjustable PID regulator
<u>Insulation resistance</u>	> 1 MOhm 500 V DC for 1 minute to earth
<u>Noise level</u>	69.9 dB 86/188/EEC
<u>Vibration resistance</u>	1.5 mm peak to peak 2...13 Hz IEC 60068-2-6 1 gn 13...200 Hz IEC 60068-2-6
<u>Shock resistance</u>	15 gn 11 ms IEC 60068-2-27
<u>Environmental characteristic</u>	Chemical pollution resistance class 3C3 EN/IEC 60721-3-3 Dust pollution resistance class 3S3 EN/IEC 60721-3-3
<u>Relative humidity</u>	5...95 % without condensation IEC 60068-2-3
Ambient air temperature for operation	5...122 °F (-15...50 °C) without derating) 122...140 °F (50...60 °C) with derating factor)
	69.9 dB
<u>Pollution degree</u>	2
<u>Ambient air transport temperature</u>	-40...158 °F (-40...70 °C)
<u>Ambient Air Temperature for Storage</u>	-40...158 °F (-40...70 °C)

Ordering and shipping details

Category	22277-ATV930 FRAMES 3 & 4
Discount Schedule	CP4E
GTIN	3606480883477
Returnability	Yes
Country of origin	IN

Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	25.98 in (66 cm)
Package 1 Width	18.90 in (48 cm)
Package 1 Length	40.55 in (103 cm)
Package 1 Weight	197.98 lb(US) (89.8 kg)

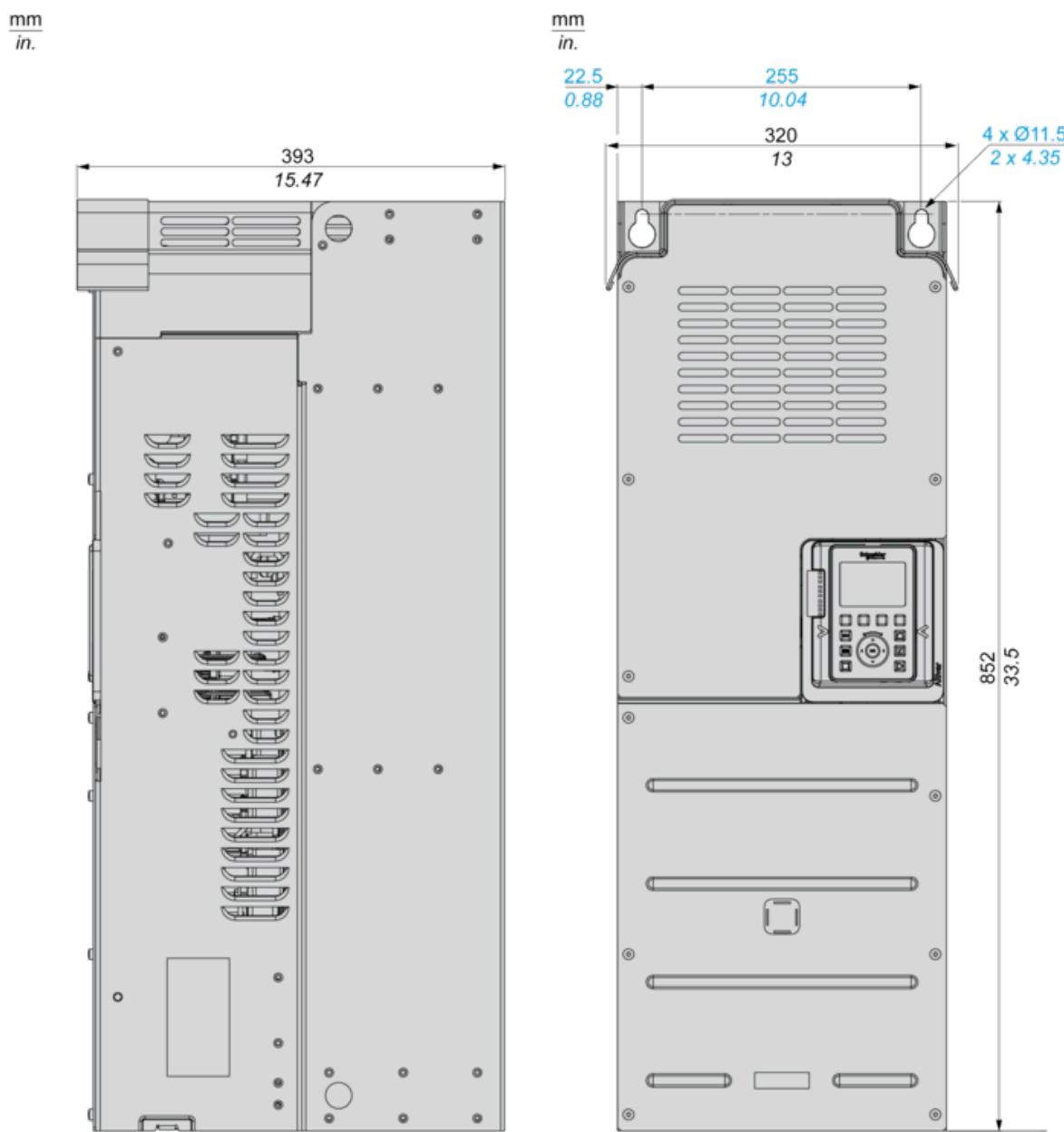
Offer Sustainability

Sustainable offer status	Green Premium product
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California proposition 65	WARNING: This product can expose you to chemicals including: Lead and lead compounds, which is known to the State of California to cause cancer and birth defects or other reproductive harm. For more information go to www.P65Warnings.ca.gov
REACH Regulation	REACH Declaration
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope) EU RoHS Declaration
Mercury free	Yes
China RoHS Regulation	China RoHS declaration
RoHS exemption information	Yes
Environmental Disclosure	Product Environmental Profile
Circularity Profile	End of Life Information
WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins.
Upgradeability	Upgraded components available

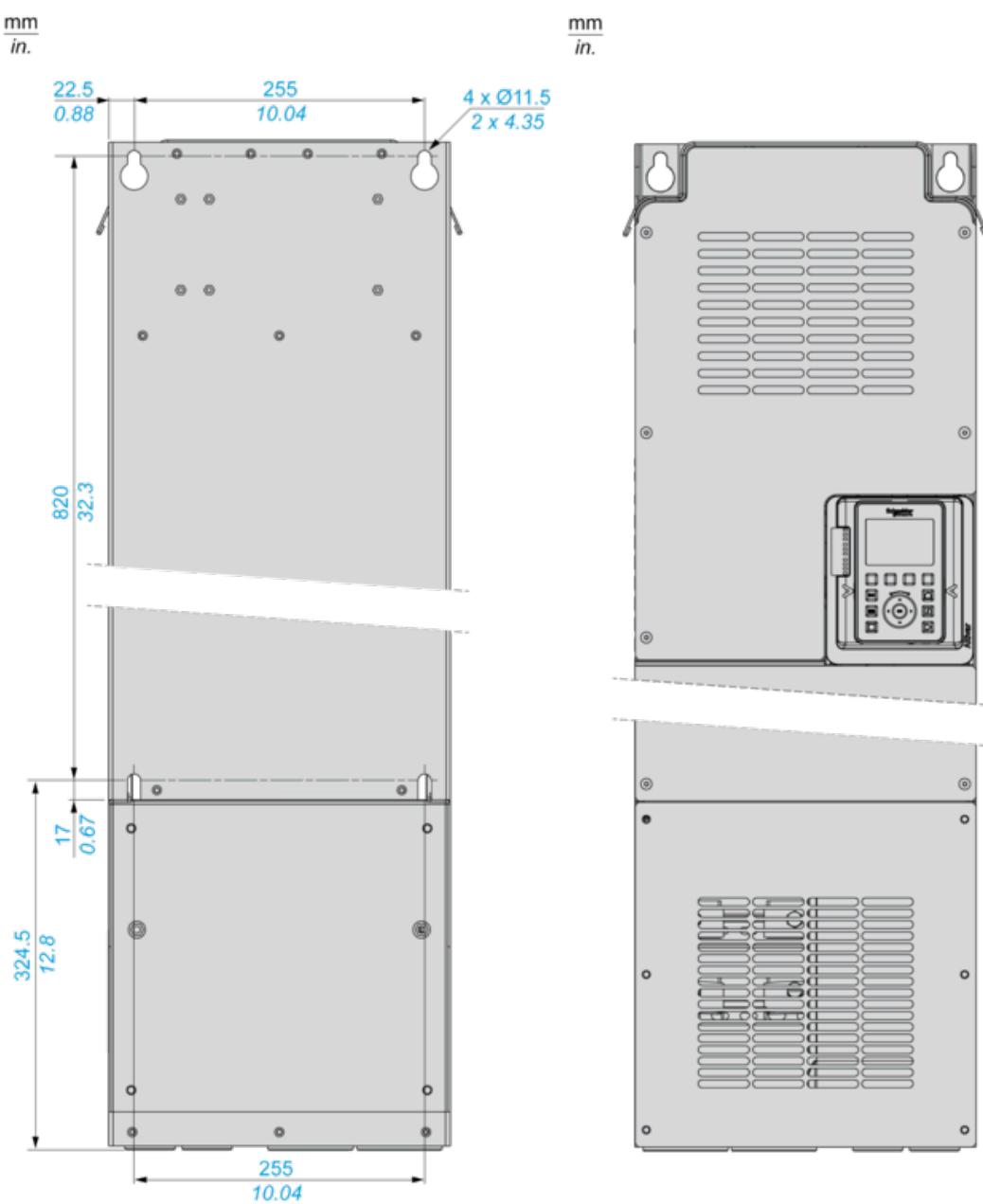
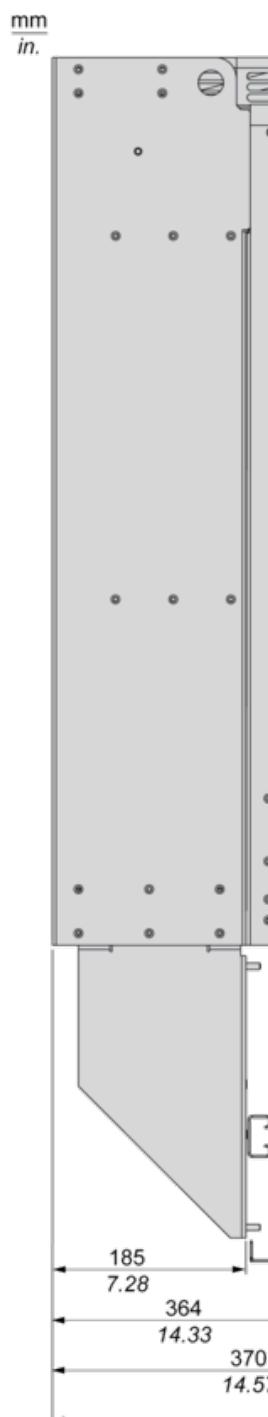
Dimensions

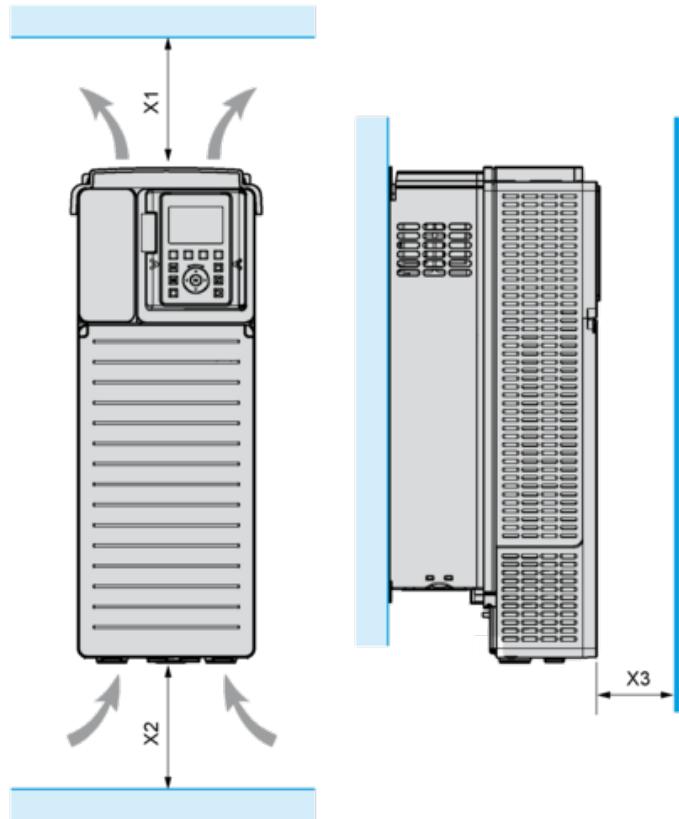
Right and Front View



Drives with Lower Conduit Box Sold Separately

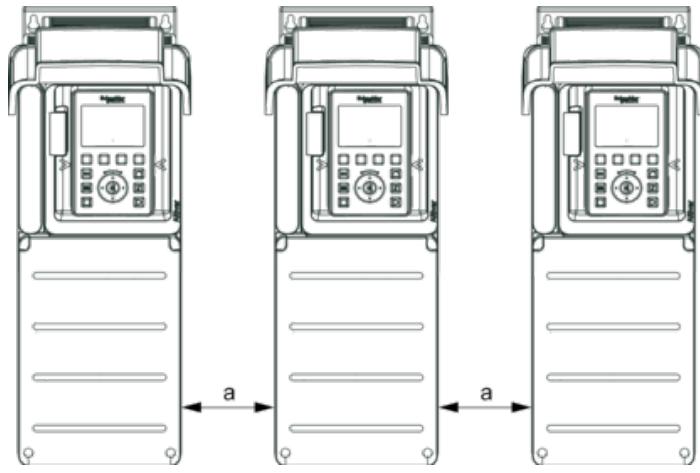
Rear, Front and Left View



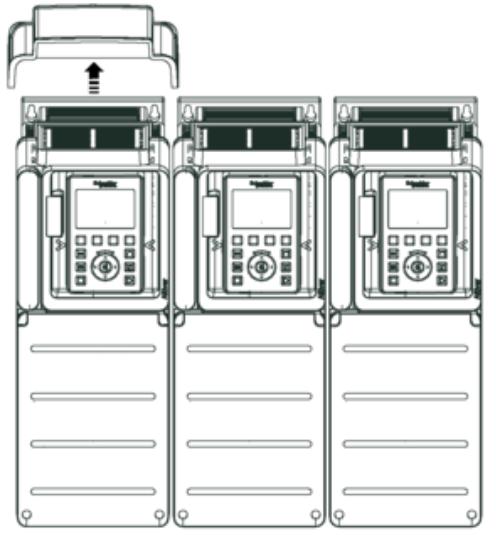
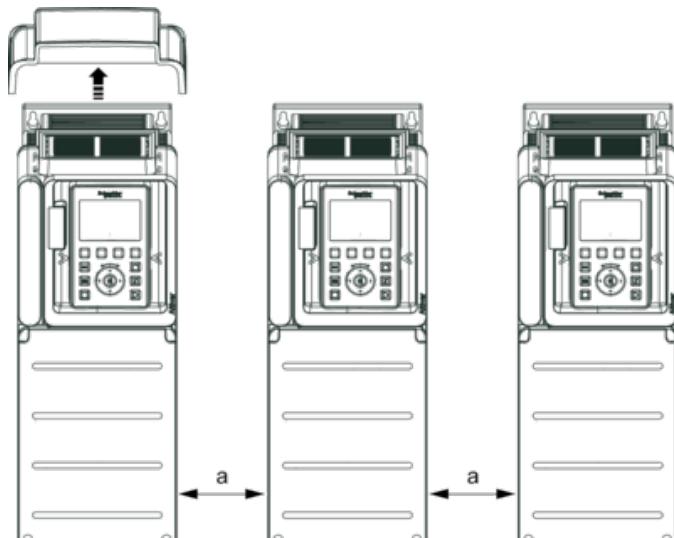
Clearances

X1	X2	X3
≥ 250 mm (10 in.)	≥ 250 mm (10 in.)	≥ 100 mm (3.94 in.)

- Mount the device in a vertical position ($\pm 10^\circ$). This is required for cooling the device.
- Do not mount the device close to heat sources.
- Leave sufficient free space so that the air required for cooling purposes can circulate from the bottom to the top of the drive.

Mounting Types**Mounting Type A: Individual IP21**

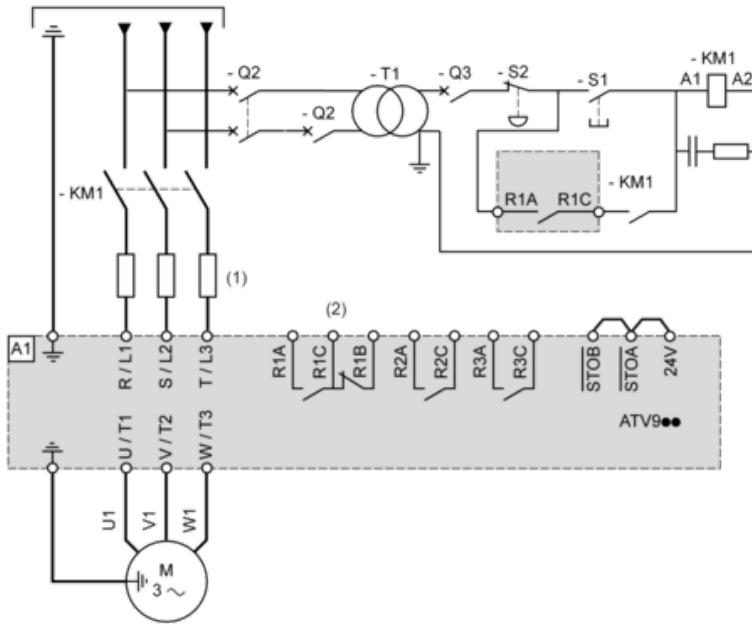
$a \geq 110 \text{ mm (4.33 in.)}$

Mounting Type B: Side by Side IP20 , Only possible at ambient temperature lower than 40 °C (104 °F)**Mounting Type C: Individual IP20**

$a \geq 110 \text{ mm (4.33 in.)}$

Three-Phase Power Supply with Upstream Breaking via Line Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



(1) Line choke if used

(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.

A1 : Drive

KM1 : Line Contactor

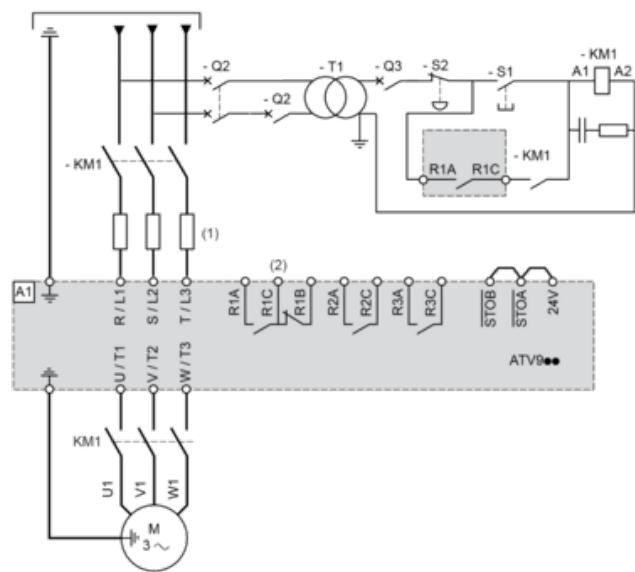
Q2, Q3 : Circuit breakers

S1, S2 : Pushbuttons

T1 : Transformer for control part

Three-Phase Power Supply with Downstream Breaking via Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1

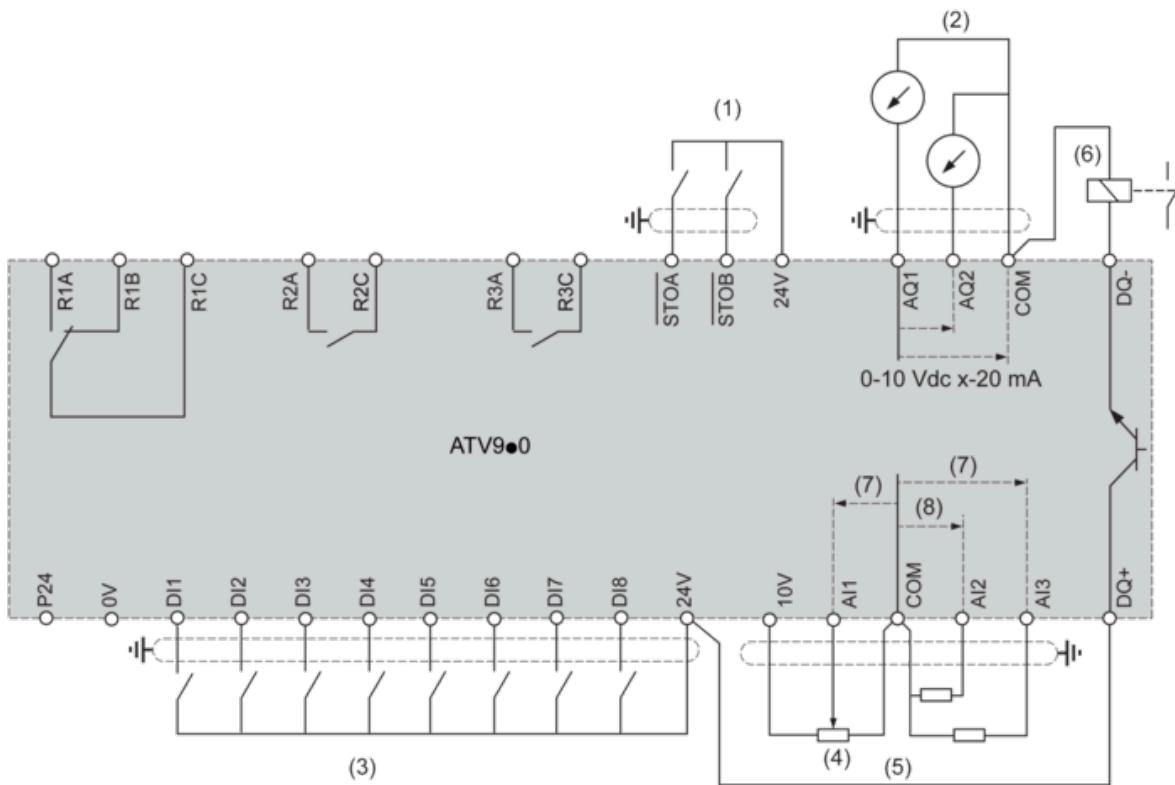


(1) Line choke if used

(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.

A1 : Drive

KM1 : Contactor

Control Block Wiring Diagram

(1) Safe Torque Off

(2) Analog Output

(3) Digital Input

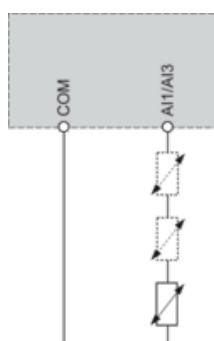
(4) Reference potentiometer

(5) Analog Input

(6) Digital Output

(7) 0-10 Vdc, x-20 mA

(8) 0-10 Vdc, -10 Vdc...+10 Vdc

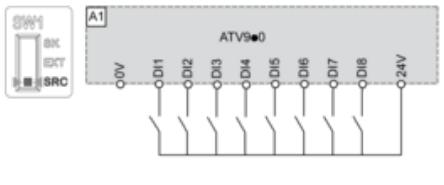
R1A, R1B, R1C : Fault relay**R2A, R2C :** Sequence relay**R3A, R3C :** Sequence relay**Sensor Connection**It is possible to connect either 1 or 3 sensors on terminals **AI1** or **AI3**

Sink / Source Switch Configuration

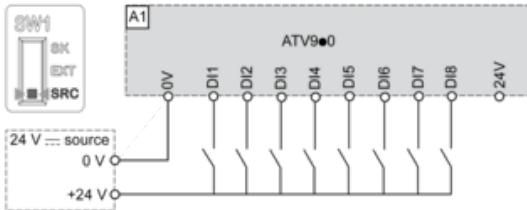
The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

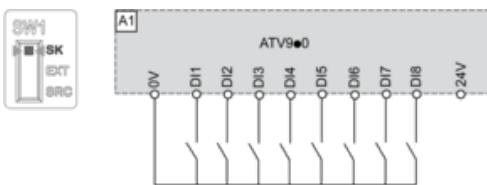
Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs



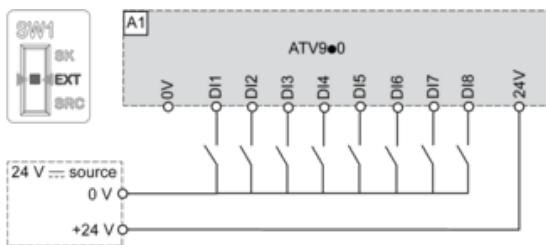
Switch Set to SRC (Source) Position and Use of an External Power Supply for the DIs

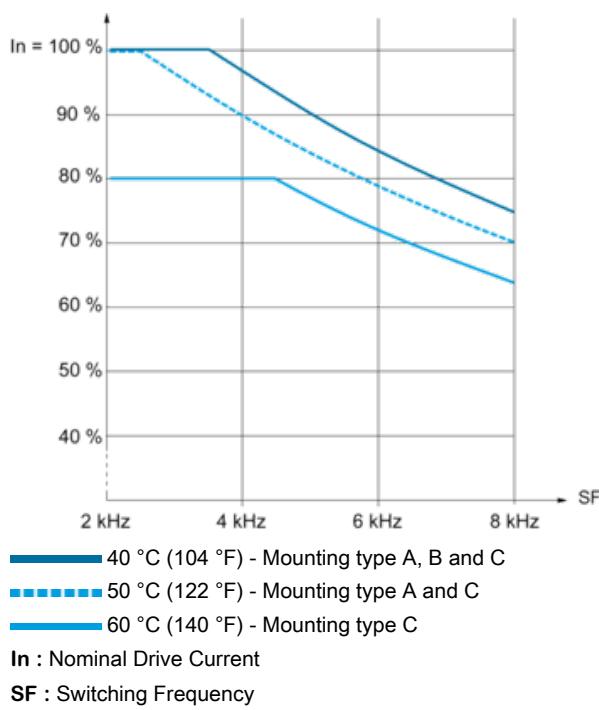


Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs



Switch Set to EXT Position Using an External Power Supply for the DIs



Derating Curves**Recommended replacement(s)**